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Correction model Final Exam Linear Algebra 2
April 3, 2018

⑧ 1. a) $\text{Span}\left(\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right) = \text{Span}\left(\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right)$. These are already orthogonal, so we only need normalization: $\|\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}\| = \sqrt{3}$, $\|\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\| = 1$. An orthonormal basis is then $\left\{ \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$

b) The closest vector in S to $\begin{pmatrix} a \\ b \\ a \\ b \end{pmatrix}$ is the orthogonal projection

⑦
$$P = \left\langle \begin{pmatrix} a \\ b \\ a \\ b \end{pmatrix}, \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\rangle \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \left\langle \begin{pmatrix} a \\ b \\ a \\ b \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\rangle \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$= \frac{2a+b}{3} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

2. a) The characteristic polynomial of A is $P_A(s) = \det \begin{pmatrix} a-s & b \\ c & d-s \end{pmatrix} = (a-s)(d-s) - bc$

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$$= s^2 + (-a-d)s + \cancel{ad} ad - bc$$

By Cayley-Hamilton we have $P_A(A) = 0$ so we should choose $\alpha = -a-d$ and $\beta = ad - bc$.

b) For the given matrix A we have

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$$P_A(s) = (-1)^4 (s^4 + ds^3 + cs^2 + bs + a)$$

So take $\alpha = d$, $\beta = c$, $\gamma = b$, $\delta = a$

3 a) We first compute $M^T M = \begin{pmatrix} 85 & -30 \\ -30 & 40 \end{pmatrix}$ (2)

Then the eigenvalues of $M^T M$:

(3)
$$\det \begin{pmatrix} s-85 & 30 \\ 30 & s-40 \end{pmatrix} = s^2 - 125s + 2500$$

$$= (s-100)(s-25)$$

\Rightarrow Eigenvalues are $\lambda_1 = 100$, $\lambda_2 = 25$
 The singular values are $\sigma_1 = \sqrt{\lambda_1} = 10$ and
 $\sigma_2 = \sqrt{\lambda_2} = 5$

b) The V -matrix is $V = (v_1, v_2)$ with v_1, v_2 eigenvectors of $M^T M$ corresponding to 100 and 25

$$\begin{pmatrix} 85 & -30 \\ -30 & 40 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 100x \\ 100y \end{pmatrix} \Leftrightarrow \begin{cases} -15x - 30y = 0 \\ -30x - 60y = 0 \end{cases}$$

$$\Leftrightarrow x + 2y = 0. \text{ This yields: } v_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

(8)
$$\begin{pmatrix} 85 & -30 \\ -30 & 40 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 25x \\ 25y \end{pmatrix} \Leftrightarrow \begin{cases} 60x - 30y = 0 \\ -30x + 15y = 0 \end{cases}$$

$$\Leftrightarrow -2x + y = 0. \text{ Yields: } v_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow V = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix}$$

We want to have $U \Sigma V^T = M$, so must find U s.t. $M V = U \Sigma$, equivalently

$$M v_1 = \sigma_1 u_1 \text{ and } M v_2 = \sigma_2 u_2.$$

Therefore $u_1 = \frac{1}{\sigma_1} M v_1 =$

$$\frac{1}{10} \frac{1}{\sqrt{5}} \begin{pmatrix} 6 & 2 \\ -7 & 6 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \frac{1}{10\sqrt{5}} \begin{pmatrix} 10 \\ -20 \end{pmatrix}$$

$$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$u_2 = \frac{1}{\sigma_2} M v_2 =$$

$$\frac{1}{5} \frac{1}{\sqrt{5}} \begin{pmatrix} 6 & 2 \\ -7 & 6 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \frac{1}{5\sqrt{5}} \begin{pmatrix} 10 \\ 5 \end{pmatrix} =$$

$$\frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow U = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}$$

Singular value decomposition of M :

$$M = \underbrace{\frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}}_U \underbrace{\begin{pmatrix} 10 & 0 \\ 0 & 5 \end{pmatrix}}_{\Sigma} \underbrace{\frac{1}{\sqrt{5}} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix}}_{V^T}$$

c) Best rank 1 approximation is

$$\frac{1}{\sqrt{5}} \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 10 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} =$$

$$\frac{1}{5} \begin{pmatrix} 10 & 0 \\ -20 & 0 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 20 & -10 \\ -40 & 20 \end{pmatrix}$$

$$= \frac{1}{5} \begin{pmatrix} 4 & -2 \\ -8 & 4 \end{pmatrix}$$

(3)

(4)

(4)

4. a) A is symmetric and real. Let λ be an eigenvalue of A . Then there exists $x \neq 0$ such that $Ax = \lambda x$. This implies $x^H Ax = \lambda x^H x = \lambda \|x\|^2$. I prove now that $x^H Ax$ is real:

$$\overline{x^H Ax} = (x^H Ax)^H = x^H A^T x = x^H Ax.$$

Thus $x^H Ax$ must be real. We conclude

$$\lambda = \frac{x^H Ax}{\|x\|^2} \in \mathbb{R}$$

b) A is symmetric so there exists an orthogonal matrix Q s.t. $Q^T A Q = \Lambda$ with Λ diagonal, eigenvalues on the diagonal:

$$\Lambda = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \dots & \\ & & & \lambda_n \end{pmatrix}$$

I will prove that $A \geq 0$ implies $\lambda_i \geq 0$ ($i=1, \dots, n$)
Take i arbitrary. Let e_i the i th standard basis vector in \mathbb{R}^n and define $x_i = Q e_i$.
Then since $A = Q \Lambda Q^T$ we have

$$\begin{aligned} 0 \leq x_i^T A x_i &= e_i^T Q^T Q \Lambda Q^T Q e_i \\ &= e_i^T \Lambda e_i = \lambda_i. \end{aligned}$$

This shows $\lambda_i \geq 0$.

c) By part b, $A = Q \Lambda Q^T$, Q orthogonal.
Take an arbitrary $x \in \mathbb{R}^n$. I will show that $x^T A x \geq 0$. Indeed:

$$x^T A x = x^T Q \Lambda Q^T x = (Q^T x)^T \Lambda Q^T x \quad (5)$$

Define $y \in \mathbb{R}^n$ by $y = Q^T x$. Then

$$(Q^T x)^T \Lambda Q^T x = y^T \Lambda y = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$$

Since $\lambda_i \geq 0$ and $y_i^2 \geq 0$ we find that

$$x^T A x = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2 \geq 0.$$

5. a) A is $m \times n$, $B = n \times m$, so both AB and BA are well-defined. Let $\lambda \neq 0$. Assume λ an eigenvalue of AB with eigenvector x : $ABx = \lambda x$. Then

(3) $BABx = \lambda Bx$. Note that $Bx \neq 0$ since otherwise λx would be 0, which contradicts $\lambda \neq 0$ and $x \neq 0$. Hence Bx is an eigenvector of BA with eigenvalue λ . Conversely: same argument.

b) $a^T b$ is a (real) number. As 1×1 matrix it has eigenvalue $a^T b \neq 0$.

(2) By part a then $a^T b$ is an eigenvalue of $b a^T$ ($n \times n$ matrix)

c) Write $a^T = (a_1, a_2, \dots, a_n)$, $a_i \in \mathbb{R}$. At least one $a_i \neq 0$ for otherwise $a^T b$ would be 0.

(3) Now $b a^T = b(a_1, a_2, \dots, a_n) = (a_1 b, a_2 b, \dots, a_n b)$. Since this matrix consists of columns that are a multiple of b we have $\mathcal{R}(b a^T) = \mathcal{R}(b)$.

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d) $\text{rank}(ba^T) = \dim R(ba^T)$
 $= \dim R(b)$

3) We know $b \neq 0$ since otherwise we would have $a^T b = 0$.

Hence $\dim R(b) = 1$ so $\text{rank}(ba^T) = 1$

e) By the dimension theorem we have

$$\text{rank}(ba^T) + \dim N(ba^T) = n$$

4) Hence $\dim N(ba^T) = n-1$. There are therefore $n-1$ independent vectors x_1, \dots, x_{n-1} s.t.

$ba^T \cdot x_i = 0$. Each x_i is an eigenvector with eigenvalue 0 so the geometric multiplicity of eigenvalue 0 is $n-1$.

6. a) Two cases: 1) $a=b$: Then the eigenvalues are a, a, a, a , algebraic mult. is 4

3) 2) $a \neq b$: then the eigenvalues are a, a, b, b , both with alg. multiplicity 2

b) $a=b$

c) Assume $a \neq b$. It can be seen that $\dim N(M-aI)$ and $\dim N(M-bI)$ are both equal to 2. Hence the Jordan form

i) simply $J = \begin{pmatrix} a & 1 & 0 & 0 \\ 0 & a & 0 & 0 \\ 0 & 0 & b & 1 \\ 0 & 0 & 0 & b \end{pmatrix}$